## SINO

## DIGITAL READOUTS

## SDS2MS

Operation Manual

فروشكاه كانون ابزار<br>تلفن :<br>موبايل : 30231470912<br>www.ali5.ir

## Dear Users:

1, Thank you for purchasing the products of the digital readout device of Guangzhou Lokshun CNC Equipment Ltd. "Sino", " $\mathbf{S}^{\mathbf{\prime}}$ is its registered trademark. It is a precision measurement products and mainly for various types of manual machine tools machining or testing equipment to provide a Detection and localization function.

2, Guangzhou Lokshun CNC Equipment Ltd has the" $\mathbf{S}^{\prime \prime}$ registered trademarks.
Notice : Please read the following safety instructions and precautions for safety operation of the new digital display meter device.

## When using the manual:

- Chapters and sections are listed in the table of contents see P5 ahead).
- This manual includes some instructions for panel keys of SDS2MS digital display meter and other series, including.

SDS2MS the readout used for 2 axis milling machine and grinding machine and lathe machine

## It is recommended that:

- Instructions for panel keys of the SDS2MS digital display meter that is applicable to this manual are listed in P1~4 of the above Section 1.
- Read through follow safety precautions and Section 2( which are very important to the safe operation of your digital display meter.


## Safety Precautions:

## Caution:

- Do not dampen or splash coolant directly onto the unit to avoid electric shock or fire.


## Warning:

- Do not open the enclosure optionally to avoid electric shock, there is no element repairable by the user inside. Turn to appointed technician for repair.
- If the unit is not used for along time, the chargeable lithium batteries for data retention inside the digital display meter will be damaged. Please contact Guangzhou Lokshun CNC Equipment Ltd. agent or professional technicians
for battery replacement when using it again.


## Notes:

- Disconnect power plug promptly if the digital display meter emits smog or peculiar smells, when an electric shock or fire may be caused when continuing to use it. Please contact Guangzhou Lokshun CNC Equipment Ltd. or dealer and never attempt to repair it by yourself.
- The digital display meter constitutes a precision detection device with an optical electronic ruler. Once the connecting wires between the two parts are broken or damaged of surface during use, error in detection data might be caused, to which the user should pay special attention.
- Do not repair or refit the digital display by yourself, otherwise a fault or damage might be caused. In the case of abnormality, please contact Guangzhou Lokshun CNC Equipment Ltd. or dealer.
- Once the optical electronic ruler used in the digital display meter is damaged, do not replace it with rulers of other brands, because products of different companies have their respective characteristics, indicators and wiring. Never make wiring without the guide of professional technicians, otherwise the digital display meter might get into fault.

CThe displacement sensor complies with 2006/95/EC directive for low-voltage electric apparatus and 2004/108/EC directive for EMC.

Our company has passed the authorization and the audit of ISO9001 Quality System, ISO14001 Environmental System, OHSAS18001 Occupational Health and Safety System.

Notice: The Interpretation of this manual belongs to Guangzhou Lokshun CNC Equipment Ltd.
Forgive product upgrades without further notice.


## Caption of the Keyboard of SDS2MS



Returning the displayed Value to zero (XAxis )

## $Y_{0}$ ———— <br> Returning the displayed Value to zero (YAxis )

## (0) (1) (2) (4) <br> Entry keys for digits

 (5) (6) (7) (8) (9)
## $\pm \otimes \rightarrow$ Operation Key (in Calculation function key)



Calculation function key (in Calculation function key)
(CA) ——— Input (calculation result) canceling key(in Calculation function key)
(2r0) —— Key for "Inverting" Trigonometric Functions (in Calculation function key)


0 Entry keys for decimal point

——Entry key plus or minus symbol ENT $\longrightarrow$ Key for entering data
$1 / 2$ ——_ Function key for getting one half
(vir) ——Key for the conversion the meter System/ British system display
$\qquad$ Function key for Sleep
$\qquad$ Function key for 200 zero Position

$R$ angular ARC function key (ARC Function key)

$\qquad$ Function key for circle equally Dividing (PCD Function key)

$\qquad$ Function key for drilling holes along an oblique line
$\qquad$ Angular surface processing function key; In calculation function as sine trigonometric function key

Progressive inner chamber processing function key; In calculation function as cosine trigonometric function key

## 包 <br> Tool compensation function key; <br> In calculation function as <br> tangent trigonometric function key

## 氷 <br> Key for the conversion of relative/absolute display

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## A. Basic Functions

فروشكاه كانون ابزار<br>تلفن : 0201663939 موبايل : 30231472912 www.ali5.ir

We take pleasure to tell you that this machine tool optical digital display ruler device you are using is the one most popular in Europe.

You will be able to use this device easily after you have read this manual thoroughly. Thank you!

## I. Usage

## 1. Start, Self check

1) Selecting the power voltage, switching the power on
2) Self check of the meter
3) Self check finished, enter working mode



|  |  |  |  | $\square$ | $\square$ | $Y_{0}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |

 "ALE"or"INC"or"ZER"

## 2. Setting of System

In process of self check, key , then the system enter setting mode after self check finished.

1) Setting axis $X$ resolution.

|  |  |  |  | $15 \times$ |  | K |  | PESILN |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

Setting different resolution according to keying different numbers.

| Number key | 7 | 8 | 9 | 1 | 2 | 5 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Resolution(um) | 0.1 | 0.2 | 0.5 | 1 | 2 | 5 | 10 |

Key (EIT) $\rightarrow$ (D) , next step
2) Setting axis $Y$ resolution.


Setting method alike axis X
Key (Bir) $\rightarrow$ (B), next step
3) Setting counts direction of axis $X$ linear encoder.

Key 0 as positive direction count.


Key 1 as reverse direction count.

$$
\text { Key (iri) } \rightarrow \text { (B), next step }
$$

4) Setting counts direction of axis $Y$ linear encoder.

Setting method alike axis X .

|  |  | (1) $\times$ | Y |  | TTIR |
| :---: | :---: | :---: | :---: | :---: | :---: |

Key (Eir) $\rightarrow$ (B), next step
5) choose compensation type
(0) choose line error compensation "LINEAR";
(1) choose Segmented error compensation
$\square$ LIINE|A|R
JEEGMENTT
"SEGMENT";
Press (Ex) $\rightarrow$ (D), next step
6) Self test.

Key (B)twice, the Self-test program started then $\odot$ key to quit.

## 3. Returning the displayed Value to zero

1) It is possible to return to zero any

## |ㅔㅔㄹㅍ4

point, take the example of X axis display.
2) $\mathrm{Key} \mathrm{X}_{2}$

## 4. Presetting data

1) As shown in the figure, after the processing of Hole A finished, the position of the working piece has been adjusted, Hole B is to be processed.
2) Align the Tool with Hole A.

3) Select the key for axis, key $X$ $\square$
4) Key 5, Enter the value(If the entered value is wrong, key $x$ and enter the correct one
 again)
5) Key ENT , (If any mistake is found now, repeat steps $3 \sim 5$ ).
6) Move the machine table to the position
 of 13 , and the processing at Point B can start.

## 5. Absolute/relative/user coordinate display mode.

Key (1) (B), the absolute/relative display mode will convert one the other, following are operations.


1) Let the Tool point to Point $M$ reset under the absolute mode.
Key ( $\because$ or $\left.(\nabla) \rightarrow Y_{0}\right)$
2) Move the machine tool to Position A.
 $\square$


3) Move the machine tool to Position. B.
$\square$ 긱.밈 (ro
4) Key (仓) $\rightarrow X_{0}$ Y0


| $\square$ | Yo |
| :--- | :--- | :--- | :--- | :--- |

5) Move the machine tool to Position C.
 $\square$

| Y |
| :--- | :--- | :--- | :--- | :--- |

6) Move the machine tool to Position D.
7) Return to the absolute mode (B)
8) Move the machine tool to Position E.

$\square$ 기임 (


17llll

$\square$ 기밈

Note: The resetting in the absolute and the relative display mode must be done separately. In absolute display mode, "ALE" is displayed on Message Screen. It is in absolute display mode when "INC" is display Message Screen.

Keying 团, (ban also realize the conversion between the two display mode, and it is also possible to enter the display mode of 200 sets of user coordinates, as shown in the following circulating schematic diagram.


Key (mand enter the display mode of 200 sets of user coordinates directly.
Enter the number

(B)

Key digit keys, such as Entered the display mode

$$
\text { (5) } \rightarrow \text { (Er) } \quad \begin{aligned}
& \text { of No. } 50 \text { set of relative } \\
& \text { coordinates. }
\end{aligned}
$$

6. (1/2) key display

As shown in the figure, the enter

between two points is to be found.

1) Move the tool along the direction of arrow and let it come to touch the one and the other edges of the working piece, then determine the center position.
2) Key axis key $x$

3) Key


4) Move the machine tool to bring the
 axis displayed value into zero, and the center position is reached.
7. "M/I" (The mm System/inch System) Conversion Display.

Key (vir, the size displayed in the mm System/inch system will convert one to the other.


1) The original display is in the mm system, and the display in inch is desired.
2) Key N10
3) Move the machine tabe to 2.4
4) Enter processing mode of Hole B
5) Key (312


## 8. Linear Error Compensation

The linear error compensation function is used to make the linear correction of the system error of the grating metering system.
Correction factor $S=\left(L-L^{\prime}\right) /(L / 1000) \mathrm{mm} / \mathrm{m}$

L---the actually metered length (mm)
L'---the displayed value on digital display meter (mm)
S---the actually factor ( $\mathrm{mm} / \mathrm{m}$ ), " + " symbol means the actual length is larger, and "-" symbol means the actual length is smaller.
Compensation range: $-1.500 \mathrm{~mm} / \mathrm{m} \sim+1.500 \mathrm{~mm} / \mathrm{m}$
Example: The Actual metered length of the machine tool machine table is 1000 mm , and the display value on the digital display meter is 999.98 mm .

$$
\mathrm{S}=(1000-999.98) /(1000 / 1000)=0.02 \mathrm{~mm} / \mathrm{m}
$$

1) Select the axis $x$
modificatory coefficient used last time

$\square$ 메밈 (10)
2) Key (sin)

Note: The linear error compensation can be carried in both absolute display mode (the message screen displays ALE).

## 9. Segmented error compensation

Note: only in Metric system can do Segmented error compensation . After Segmented error compensation, the display can be converted freely betweef Metric system and Imperial system.

There are two methods for Segmented error compensation of the digital display meter:

1. To carry out error compensation taking the start point as the mechanical origin. (Figure 1)
2. To carry out error compensation taking the $1^{\text {st }}$ absolute zero of the raster ruler as the mechanical origin. (Figure 2)

(Figure 2)

L: The distance of effective range of raster ruler
L1: Length of the compensation segment
L2: Effective distance of the compensation segment

1. Set up according to the sketch map 1. The parameter set-up method is as follows:
$\square$
1) Move the raster ruler to the
) Move the raster ruler to the $\square$

smallest end of the coordinate data Enter into the ALE right-angle coordinate system
2) Press $(X \rightarrow$ M $\rightarrow$ enter into the input function of multi-segment compensation of X axis (the set-up method for Y axis and Z axis is the same as X axis.)
3) Input the quantity of compensation segments
(Figuer 1):


NUMBER
(Figuer 2):


Remarks: The quantity of compensation segments of any axis is input in X axis.
4) Input the length of compensation segments

Press $x$ X $\rightarrow$ input compensation length value $\rightarrow$ ENT
Press ( (B), next step

5 ) Find the mechanical origin
There are two methods for setting the compensation origin. $\square \mathcal{L}|E| F|=|E| R|$ 1, directly press ENT to choose the current position as origin.
2, Press $\rightarrow$ HA $\rightarrow$ to choose the 1 st absolute zero of the raster ruler as the mechanical origin.


Move towards the positive direction of X axis of the machine tool and search for the 1st absolute zero of the raster ruler as the mechanical origin. After find the origin, then auto enter the next step for data input. This time the X -axis displays the raster ruler fact value, and Y -axis displays the former compensation value(if the readout is first compensated, the Y -axis display a uncertain value).
6) Input the compensation setup of the $1^{\text {st }}$ segment

At this time, firstly move the

positive direction. When the raster ruler is moved around the length of the compensation value (the compensation length in Step 4 is $\pm 0.5 \mathrm{~mm}$ ), the display of Y axis is dimmed and enters into the status of value setting status, at this time input the standard value of Y axis or the exact value measured by laser (this method is implemented in every set-up point)
Press $1 \rightarrow 0 \rightarrow$ (Ev)
(When press , Y-axis will displays the X -axis's value, and that means the compensation value has been setup. If the value input is wrong, don't move the raster ruler, and press (t) , then press (B), this time the digit-display LED of Y-axis will be in input state, and input the right value again.)

Press (D) and enter into the next set-up point
Remarks: In this function, the display of X
axis is the coordinate value, while Y axis
displays the standard value or the
measurement value by laser
coordinate value


The standard value or the measurement value by laser
7) Input the compensation setup of the 2 nd segment

Press


Press (v), enter into the next set-up point
8) Input the compensation setup of the 3rd segment

$\square$


9) Input the compensation setup of the 4th segment


Press (B), and enter into the next set-up point
10) Input the compensation setup of the 5th segment


Press (B), and enter into the next set-up point
11) Input the compensation setup of the 6th segment


After the setup is finished, press mey to exit.
Remarks: The input zone for the compensation value of Y axis and Z axis is the coordinate display zone of X axis.

## 2. The cancellation method of Segmented compensation value

The Segmented compensation value is only aimed at the digit display meter, raster ruler and machine tool set up together. If the raster ruler or digit display meter whose Segmented compensation value is set up in a machine tool is moved to another machine tool, the Segmented compensation value needs to be reset. When the Segmented compensation function is not needed, the Segmented compensation value is to be cancelled. The cancellation method is:

According to the set-up method of Segmented compensation indicated above, when it is indicated to input the quantity of compensation points, input 0 as the compensation segment, then all the compensation setup parameters are initialized. At this time, all the compensation values set up before are cancelled automatically.

## 3. Finding the function of the mechanical origin

If there is power off when the raster ruler is moving, or the rater ruler is moved before the power is on, after re-start, the mechanical origin needs to be found again. Because of movement in power off or before power on, the coordinate origin of the machine tool can not match the value in the digit display meter. If the mechanical origin is not found, the misplaced relationship is brought into the later user coordinate system. As when calculating the user coordinate, the

Segmented compensation value is found according to the wrong mechanical coordinate, thus there is big error of the displayed coordinate.

The method of finding mechanical origin is as follows:

1. Move the raster ruler to the position which is initially set up as the mechanical origin, and then set up Segmented compensation. When inputting the quantity of compensation segment and the compensation length, do not make any change, and press (B) directly to skip. Enter into the interface for choosing compensation method, press EnT . The interior of digit display meter handles automatically. At this time, directly press mey to quit the Segmented compensation setup, and finish finding the mechanical origin.(Remarks: It is applicable to setting up parameters according to sketch map 1)

2 .Firstly move the raster ruler to the smallest value, and then set up Segmented compensation. When inputting the quantity of compensation segments and the compensation length, do not make any change, and press (B). directly to skip. Enter into the interface for choosing compensation method, press $\rightarrow$ EnT , to enter X axis to find the status of absolute zero. Move the raster ruler towards the positive direction. When the absolute zero is found, it is the mechanical origin. The interior of digit display meter handles automatically. At this time, directly press mey to quit the Segmented compensation setup, and finish finding the mechanical origin.(Remarks: It is applicable to setting up parameters according to sketch map 2)

Note: When find the mechanical origin, the user-coordinate will resume.
Advise: find the mechanical origin before start work after power on to assure the coordinate origin of the machine tool can match the value in the digit display meter.

## 10. Power Interruption Memory

During the processing of a working piece, there may occur power interruptions or needed temporary turnoffs, the digital display box will automatically store the working state (such as the working mode in every axis, displayed data and the linear error compensation factor) just before every interruption event in its memory. Every time when the machine is turn on again, the digital display box will recover to its working state just before the interruption event after self checking, and the valve just before the interruption (turn off) event will recover, and the processing will continue.

## 11. Sleep Switch (no this function for the digital display box with 3-axis display)

The switch on the back panel of the digital display box may once be turned off during the processing of a working piece. It is true that the SDS2MS Series digital box has its interruption memory, but the machine tool may have been moved after the event. In such a case, when the machine is turned on again, the working state just before the interruption event will be displayed again, but this is not the actual new situation. If the operator want to suspend the processing for his (her) rest time or any time he (she) is occupied by other thing, the sleep switch can be used to avoid the above mentioned situation.

In not ALE working state, if there a need of Sleep Switch Off, key [HA , the digital display box will turn off the display. When restarting the processing, key ${ }^{\text {HAA }}$, and the box will turn on all the display. No matter how the machine tool was moved after the display had been turned off, the box will "see" and "keep in mind" the end state after the machine tool have been moved. When the display has been turned on again, the displayed working state will be the actual state.

Note: When the sleep switch has been turned off, the digital display box is not really in the turnoff sate; if the power switch on the back panel of the box has been turned off, the sleep switch losses its function.

## B. Smooth R

## Smooth R Arc Calculation function (ARC Function)

In the processing of moulds, it often happens that the processing of circular arc is indispensable. For the case that the processing is arranged for a single working piece, the required contour is simple and not too much processing of circular arc will be involved, it may involve much dissipation in both time and money to arrange the job to a digital control machine tool.

The advanced smooth R arc Calculation function provided in SDS2MS model digital display box makes it possible to complete the processing of a single piece such as moulding copper electrode easily and quickly with a universal milling machine. This arc Calculation function makes it possible to freely control the smoothness of the circular arc. The distance between two adjoining working points is uniform, the smoothness of the circular arc can be control through the control of this distance.

This function is used in the processing of circular arc. (1)The display on the message window prompts the operator to enter all the parameters have to be defined, so it is very easy to operate. (2)This function can based on the input maximal cut (MAX CUT) calculates out the most proper depth of cut, and so, the smoothness of the circular arc in thoroughly in the operator's control.

1) An operator without experience in this must at first get a clear understanding of the coordinate system in using the Arc R calculating function.

Note: The arrow direction is the positive direction of coordinate axes.

2) Let us recognize the plane coordinate and the start and end angles of a circular arc.
In Plane XY, XZ or YZ, the coordinate of a point is its position with respect to the zero point on the plane.


The coordinate of zero point $\mathrm{O}:(0,0)$
The coordinate of Point $\mathrm{A}:(20,20)$
The coordinate of Point B: $(30,10)$
The coordinate of Point C:(-20,20)
The coordinate of Point D:(-30,10)
The coordinate of Point E: $(-30,-10)$
The coordinate of Point F:(-20,-20)
The coordinate of Point G:(30,-10)
The coordinate of Point H:(20,-20)
Fig. 2
In Plane XY, XZ or YZ, the start and end angle of a circular arc is counted in anti clockwise.

Fig. 3
As shown in Fig. 3:


From A to B $0^{\circ} \longrightarrow 90^{\circ}$
From B to A $90^{\circ} \longrightarrow 0^{\circ}$
From C to B $90^{\circ} \rightarrow 180^{\circ}$


3) The procedure in using the Arc R Calculation function.

As shown in the figures(a), (b)and (c), reset all the axes after finishing the installation of Tool and the related tool setting (assign the position of the tool after tool setting as the zero point).

Key (D), enter the Arc R Calculation function.

## 1. Select the smooth $R$ function (SMOOTH).

2. Select the processing plane $X Y$, $X Z$ or $Y Z$.
(ARC-XY)
(ARC-XZ)
(ARC-YZ)


## 3. Enter the center position of the circular arc:(CT POS)

The center position of the circular arc is the position of the circle with respect to the position of the tool just after tool setting and reset.


In the processing the arc in XZ or YZ plane:
As shown in Fig. (b) when a flat end milling tool is used, the circle center position is the position of Point O with respect to Point B on the tool.

As shown in Fig. (c) when a circular arc milling tool is used, the circle center position is the position
 of Point O with respect to Point C on the tool.

In the processing of the arc in Plane XY, as shown in Fig. (a), the circle center position is the position of the center axis of the tool.

## 4. Enter the radius of the circle (RADIUS)


(d)

## 5. Enter the diameter of the tool (TL DIA)

Note: In the processing of the arc in Plane XZ or YZ, as show in Fig. (b) an end mill is used and the working point is Point B , the diameter of the tool is not involved in the processing, so, you must enter (TL DIA) $=0$.

## 6. Enter the maximal cut (MAX CUT)

When this function is used in the processing of circular arc, the cut of every cutting feed is uniform, as shown in Fig. (d).

## 7. Enter the start angle of the circular arc (ST ANG)

This determines the position of the first cut feed in the processing of circular arc. As show in Fig.(b), the start angle is $0^{\circ}$ if the arc is to be processed from Point E to Point F , and $90^{\circ}$ when from F to E .
8. Enter the end angle of the arc (ED ANG)

This determines the position of the last cut feed in the processing of circular arc. As shown in Fig. (b), the end angle is $90^{\circ}$ if the arc is to be processed from Point E to Point F , but 0 when from F to E .

## 9. Determine inner/outer circle mode:

For outer circular arc, as shown in Fig. (b), RAD+TL.
For inner circular arc, as shown in Fig. (c), RAD -TL.
10. Move the machine tool to the start point of the processing in following with the display on axes, and then start the point by point processing.

## 11. You can quit the Arc $R$ Calculation function as will, just key $\otimes$.

( I ) *Take the processing of the arc shown in the figure in page 22 as an example.

1) At first, finish tool setting, reset, key (D), and enter ARC function.
2)choose smooth function
press (iri)
$\square \square$ SIMPLE
$\square \square$ SMDUTH
$\square \triangle M M D T T H$
2) Select processing plane

> Key (0) or (r)

|  |
| :---: |
|  |  |
|  |

4) Select Plane XY

Key (Ein)

|  |
| :---: |

5) Enter the position of the circle center.

If finish the tool setting as shown in Fig. (a).


Key (J)

If finish the tool setting as shown in Fig. (b).


$$
(\mathrm{Y}) \rightarrow(2) \rightarrow(2) \rightarrow(5) \rightarrow( \pm) \rightarrow(\text { (in) }
$$

Key (J)


D 6) Enter the radius of the circle.
$\mathrm{Key} \rightarrow(0 \rightarrow$ (in)
Key (8)

-     - 리림ㅁ (x)
- 기리미 (


7) Enter the diameter of the tool.

Key (5) $\rightarrow$ (air)
Key (B)

$\square \square|T|$ ®

$\square$

$\square$
(r0)
Key (B)

$\mathrm{Key}(\mathrm{O} \rightarrow$ (הi)
Key (3)
$\square$
10) Enter the end angle of the arc.
$\mathrm{Key}(9) \rightarrow(0) \rightarrow$ (in)
Key (3)

$\square$
11) Determine inner/outer circle mode.

Key (1) O ( $\sqrt{5}$
Key (sin)

| \|R,4] $\mid+T$ TLL |
| :---: |
| \|R,A]I-TTL |
| 111111 |

12) It is display that the processing start at the first point.
Tool setting as Fig. (a)

Tool setting as Fig. (b)

$\square 122.501$ (


- [ 2 2 5 [0


| 1 |  | $\square$ |
| :--- | :--- | :--- | :--- |

14) Key (8) or (1) and the position of any processing point may come to be displayed, and you can move the machine tool to bring the displayed values on the both axes into zero and reach the position of the corresponding point of the R circular arc.
(II) *Take the processing of the working piece shown in the figure on the right as the third example:

## 1. For the processing of this working piece, it is

 necessary to calculate out the start and end angles of the are at first.Refer to the figure.

$\alpha=\operatorname{arc} \cos (17.3 / 2) / 10 \approx 30^{\circ}$
The start angle (ST ANG)of the arc is $30^{\circ}$, and the end angle (ED ANG) is $150^{\circ}$.

2. At first, finish tool setting and return the boring ring scales on X - and Z - axes to zero.

1) Key , enter ARC function.

2)choose smooth function
2) Select processing plane.



3) Select Plane XZ.

Key

$\square[|T| P|0| S]$


Key (B)



Key (1) $\rightarrow$ (0) $\rightarrow$ Key (B) $\square$
*Now a circular arc mill is used, finish the tool setting as shown in Fig. (b)
7) Enter the diameter of the tool.

Key (5) $\rightarrow$ (ax)
Key (3)
8) Enter the maximal cut.

9) Enter the start angle of the arc.
$\mathrm{Key}(1)$
$\mathrm{Key}(D)$$(5) \rightarrow(\mathrm{BH}$
10) Enter the end angle of the arc.
$\mathrm{Key}(3) \rightarrow$ (20)
Key (3)
11) Determine inner/outer circle mode.

Key ( (1) or (3)
Key (in)
Key (B)

$\square$

$\square$

$\square$

$\square$

$\square$
$\square$
12) It is display that the processing start at $\square$
$\square$ the first point.
13) enter the processing and display the first point.


-     - 

14) Press (J) or to display the every processing position, Move the machine tool to bring the display value on X - and Y-axes into zero, that's the each point of R.

You may quit ARC function at will, just key .

## C. Simple R

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## Simple Are R Calculation function:

One who is not quite at home in the concepts of plane coordinates will feel difficult in using smooth arc function. If the arc to be processed is simple enough, and the required smoothness is average, the simple arc R function may be a good choice.
In general, the processing of a circular arc will be realized in one of the eight ways shown below, using end mill or circular arc mill.

*The operation procedure of the simple arc $\mathbf{R}$ function.
Let the tool face just at the arc, and key , enter arc R Calculating function. As to how to let the tool face just at the start point, just refer to (1) in page 30.

1. Select the simple R function (SIMPLE).
2. Select the processing way among the preset 1 to 8 ways, the prompt: "WHICH".
3. Select the processing plane, $\mathrm{XY}, ~ \mathrm{XZ}$ or YZ .
(ARC-XY)
(ARC-XZ)
(ARC-YZ)
4. Enter the of the circular arc (RDDIUS)
5. Enter the diameter of the tool (TL DLA): When processing the arc in Planes XZ and YZ, end mill is used and the processing in carried by the end edge of the tool, so the diameter valve to be entered should be zero.(refer to step 5 in the operation procedure of the smooth R function).
6. Enter the maximal cut (MAX CUT):

When processing an arc in Planes XZ and YZ, "MAX CUT" in the simple R function is defined as the depth of cut in each cut feed in Z axis direction (see Fig. a) the maximal cut can be changed during the processing. When processing an arc in plane XY,


Fig. (a)


Fig. (b)
"MAX CUT" is the cut of each cut feed and is uniform (refer to Fig. b).
7. Implement the processing point by point following the display.
8. You may quit the arc R Calculating function at will, just key
*Take the processing of the arc on right as an example.

) At first, let the tool face just at the start point of the arc (point A or Point B), key 包, enter ARC function.
Select the simple function key .

2) Select $R$ processing mode. Start point is A, key (3) $\rightarrow$ (air)
WHILH

End point is B, Key (4) $\rightarrow$ (Eir)


$\mathrm{L}=\mathrm{R}$

$\mathrm{L}=\mathrm{R}$

End mill

$\mathrm{L} 1=\mathrm{R}$
$\mathrm{L} 2=$ the radius of the tool

$\mathrm{L} 1=$ the radius of the tool
$\mathrm{L} 2=\mathrm{R}$
Circular arc mill
$\mathrm{L}=\mathrm{R}+$ the radius of the tool


$$
\mathrm{L} 1=\mathrm{R}
$$

$\mathrm{L} 2=$ the radius of the tool

$\mathrm{L} 1=$ the radius of the tool
$\mathrm{L} 2=\mathrm{R}$
Plane XY
3) Select the processing plane Key (1) or (3)

4) Select Plane $X Z$

Key (irir

## 

$\square$

$\square$
6) Enter the radius of the tool

Key (O) $\rightarrow$ (ix)
Key (D) $\square$
7) Enter the maximal cut

8) Start processing Key (n)

Point A as the start point $(0,0)$
Key (3)]

$\square$ 게밍


|  | L |
| :---: | :---: |

- 
- 

| \| $\times 4 \times 7$ | [ |
| :---: | :---: |


9) Refer to the display, move the machine tool to bring the displayed value on $X$ axis into zero, then turn the Z axis star wheel to let the machine table rise or drop by the display value in Y axis.
10) Key (J) or (今) and the position of next/last point will displayed.

You can quit ARC function at will, just key (B)


## ＊Take the processing of an inner circular arc as example：

1）At first，align the tool to face just the start point（Point A or Point B）， key to enter ARC function．
Select the simple function，key（air）
$\zeta I M P L E$

2）Select the way of the $R$ processing
Point A is the start point，key 6 （ax）

## WHI［H

Point A is the start point，key 5 （Ex）
3）Select the processing plane
Key（1）or（3）


4）Select Plane $X Z$
Key（ain）

5）Enter the radius of the circular arc
$\mathrm{Key}(\mathrm{D} \rightarrow$（200）
［RARIIUI］

Key（3）

$\square$
6）Enter the diameter of the tool
Key（5）$\rightarrow$（iri
Key （B）



Key $[0 \rightarrow \infty \rightarrow$（B）
Key（s）
8）Enter processing mode
Key（3）
Point A is the start point $(0,0)$
Key（ $\sqrt{3}$







9) Refer to the display, move the machine tool to bring the displayed valve on $X$ axis into zero, then turn the Z axis star wheel to let the machine table rise or drop by the displayed value in Y axis.
10) Key (B) or $\widehat{\Delta}$ and the position of next/last point will display. You may quit ARC function, just key (D).

Note: After entering processing mode, the number of the processing point and the accumulated value in $Z$ axis direction will alternately displayed on the message window.

## *Changing the maximal cut



When processing an arc in Plane XZ and YZ, "MAX CUT" is the depth of cut in Z axis. If the depth of cut in Z axis is uniform, the surface quality of the arc worked out will be very no uniform. In order to improve the surface quality of the circular arc processing in Plane $X Z$ and $Y Z$, the operator may change the maximal cut during the processing to bring a rather uniform surface quality. When processing an arc in Plane XY, "MAX CUT" is the cut of each cut feed. By reason of the cut of each cut feed in uniform, the surface quality of the arc worked out will be controlled to be rather uniform, so, no "changing the maximal cut" function will be used when processing an arc in Plane XY.

For changing the maximal cut, the operator may follow the following operations.

1) Change the maximal cut under processing mode.
Key $1 / 2$



the original entered

페1000 (

 the processing.
Key (122 $\square$

# D. Hole Drilling Along An Oblique Line 

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## The function of hole drilling along an oblique line

Normally, for processing the working pieces shown in the right figure the operator must calculate out the distance between two neighboring holes in X - and Y- axes; an easy and quick resolution is provided through the function of hole drilling along an oblique line.

What the operator shall do is only entering

(a)

## the following data:

The length of the oblique line(LENGTH)
This is the real distance from the center of the start hole to the center of the end hole, enter this data when "MODE L" (length mode) is selected.

The step length (STEP)

(b) the holes.

This data shall be entered when "MODE S " (step length mode) is selected.
Angle (ANGLE)
This is the direction of the oblique line in the plane coordinate. The angle is $30^{\circ}$ in (a), so, the plane angle to be entered is 30 ; the angle is -30 in (b), so the plane angle to be entered is -30 .

## Number of holes (NUMBER)

## Take the processing of (a) as example

1) At first move the tool to the position of the start hole A.
Key $\&$ to enter the function.
2) Select Mode

Key (1) or (B)
Select"MODE L"
Key (ain)
3) Enter the length of the oblique line


Key (B)
4) Enter the angle

Key (3) 0 ( 30
Key (B)

MDIE 3
MODE L

$\square$ प|
5) Enter the number of holes

$\mathrm{Key}(4) \rightarrow$ ENT Key (8)
$\square$
6) The position of the first hole is displayed, enter processing state.


7) Key (v) to display the position of next processing point, and then move the machine tool to bring the displayed value on both X - and Y -axes into zero. You can quit the function at will, just key

For the working piece in (a), it is more convenient to select "MODE L". In the following, we take working piece in (b) as anther example to shown how to operate when "MODE $S$ " is selected.

1) At first move the tool to the position of the start hole A.
Key 8 to enter the function
2) Select Mode

Key (1) or (3)
MODE L
MODE 5
MODE 5
Select "MODE S"
Key (ain)
3) Enter the step length
$\mathrm{Key}(2) \rightarrow(0) \longrightarrow$ (air
Key (3)
4) Enter the angle
$\mathrm{Key}(3) \rightarrow$ (3in)
Key (B)
5) Enter the number of holes

Key (4) $\longrightarrow$ (ini)
Key (B)
7) Enter processing state


데밍
8) Key (8) to display the position of next processing point, and then move the machine tool to bring the displayed value on both X- and Y-axes into zero. You can quit the function at will, just key

# E. The Function For 200 Point <br> <br> Subsidiary Zero Positions 

 <br> <br> Subsidiary Zero Positions}

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## 200 subsidiary zero position function:

200 auxiliary zero position function: also is called 200 user Coordinate System (UCS) function.

ALE: Absolute Coordinate System.
ALE is the "reference" system. All 200 UCS are defined relative to the ALE. ALE is confirmed in the initialization of the work piece process, which doesn't change if the work piece no changed.

UCS: User Coordinate System.
In the processing of moulds, often it would not work with only one reference zero position, normally, a lot of subsidiary zero positions is necessary. In the processing of a large of complicated drilling/milling fittings with multi point dimensions, it is also necessary to have a lot of fixed point positions in order to perform the processing of a series of structures with dimensions referred to these point position. In these cases, if there is only one reference point, the working efficiency will be rather low, as you have to find out the correct position point by point, more over, it may be very difficult for complicated moulds or moulding fittings to do in such a way. The function 200 point subsidiary zero positions is specially provided as a good resolution for this problem.

## I. The operator must know the following two key points before making use of this function:

1. Every subsidiary zero position is equivalently the original point of one UCS. Once entering the display mode of such UCS, the display of every point will take the subsidiary zero position as the original point.
2. There is relation between every subsidiary zero position and the zero position is the absolute mode. After a subsidiary zero position is set, it will keep the position relation between it and the zero position in the absolute mode in memory, once the zero position in the absolute mode changes, the subsidiary zero position will also change by the same distance and angle.

## II. The operator may fully make use this function as the

## following:

1. Set the zero position in absolute mode (ALE lamp on) at the main reference point of the working piece, for example, Point O in Fig. (1) in next page. Set subsidiary zero positions at subsidiary reference points of the working piece, for example, Points 1, 2 and 3 in Fig. (1). It is possible to enter the display mode of
every UCS taking a subsidiary zero position as its original points to perform the processing when need.
2. In the display mode of every UCS, processing with various special function can be performed.

## III. The setting of subsidiary zero position

There are two methods of setting subsidiary zero position: the one is entering the position of the subsidiary zero position directly, the other is resetting once a subsidiary zero position is reached.

Method 1: Directly Entering, under the UCS display mode, key $X X X$ $\rightarrow$ Number keys $\longrightarrow$ IERO .

Take Fig. (1) as example: After turning the machine on, move the machine tool to the center point O in Fig.(1), enter the absolute display mode.


Reset, set the zero position in the absolute mode at the main reference of the working piece.


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1) After setting the zero position in the absolute mode, the system automatically perform a keeping in memory operation, in order that once a power interruption happen in the course the zero position may be tracked back.
2) Enter the UCS display mode. (Two Method)

Method 1:
Key (0)
Key 甾


Method 2:
Key (zeod
Key ( $\rightarrow$ (Eir
पZERTMT1
3) Enter the position of the first subsidiary zero position.

Key

$\square$

$\square$ 기임
4) Enter the position of the second UCS.

Key (4) or 2 (200 $\rightarrow$ (2) $\rightarrow$ (Ax)

## 

5) Enter the position of the second zero position.

6) Enter the display mode of the third UCS.

$\square$
7) Enter the display mode of the third zero position.

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The setting of all the subsidiary zero positions of the working piece shown in Fig. (1) has been finished.

Why the enter position coordinates of every subsidiary zero position are just in the opposite direction of the displayed values? Let us explain this with the above example. Under the UCS mode, when the coordinates of the subsidiary zero position are entered at the position of the zero position in the absolute mode, the displayed data will be the position of the zero position in the absolute mode in the
corresponding UCS. This is because the subsidiary zero position is taken as the original point of the UCS under the relative display mode. In Fig. (1), we can see that Point $O$ is at the position $(-80,-30)$ with respect to Point $1,(-70,-40)$ with respect to Point 2, and $(-60,-40)$ with respect to Point 3. If the operator enter the coordinates of a subsidiary zero point other than the zero position in the absolute mode, the displayed data will be the position with respect to subsidiary zero point in the corresponding UCS. For example, when the position of the third subsidiary zero position is entered at Point E , the resulted display will be $(-50,-30)$.

Method 2: Clearing when the position is reached. When the machine tool is at the position of the subsidiary zero point, key $X_{0} Y_{0}$

We take the working piece shown in Fig. (1) as example again: Move the machine table to the center point $O$ shown in Fig. (1).

1) Enter the absolute display mode, reset, set the zero position in the absolute set the zero position in the absolut
mode at the main reference point.

$\square$
$\square \square]$ 밈
2) Move the machine table of the machine
-1) $\square$ tool to Point 1.
X axis display -80,

| - | $\square \square$ | $\square$ |
| ---: | :--- | :--- |

Y axis display -30,
3) Enter the display node of the first UCS.

- $\square$
Key 园 or (1200 $\rightarrow$ (2ir)


4) Set the subsidiary zero position. Key $X_{0} Y_{0}$
 $\square$


- 
- 

5) Return to the absolute state display mode Key (3)
6) Move the machine table of the machine tool to Point 2.
X axis display 70 , Y axis display-40.
$\square$
$\square$ -
7) Enter the display mode of the second UCS.
$\mathrm{Key} \rightarrow 2 \rightarrow$ (2iroc
8) Clear, set the second subsidiary zero point.
Key $X_{0} Y_{0}$
9) Return to the absolute state display mode.
Continue to touch three times key (B)
10) Move the machine table of the machine tool to Point 3.
X axis display 60 , Y axis display 40.
11) Enter the display mode of the third UCS.
$\mathrm{Key} \rightarrow$ (200 $\rightarrow$ (ENO
12) Clear, ser the third subsidiary zero point.
Key $X_{0} Y_{0}$
13) Return to the absolute state display mode.



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## 



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$\square$
$\square 14$ IOID

Continue to touch four time key (3)
The setting of all the subsidiary zero positions of the working piece shown in Fig. (1) has been finished.

## IV. The usage of subsidiary zero positions.

After entering the display mode of the UCS, the corresponding subsidiary zero positions may be used to help in the processing.

When using keys (1) and (5), you may key (1) or (8) continuously until
entering the desired UCS.
When using key just key and under the prompt "ZERO No" enter the number of the desired UCS. For the related operations, the operator may refer to "5 Absolute/relative/user coordinate display mode" under " I .Usage" of "A. Basic Function".

We take the working piece shown in Fig. (1) as example.

1) Enter the display mode of the first UCS.

Key (zan)
$\square \mathrm{F}|E| \mathrm{R}|\mathrm{D}| \mathrm{N}$
2) Enter the number.

Key (1) $\rightarrow$ (AT)

| Z $\|E\| R \mid$ | 1 |
| :---: | :---: |

3) Move the machine tool to Point A.

X axis display 0 , Y axis display 15.


4) Process Hole A.
5) Enter the display mode of the second

 UCS. Key 昷

- I I I5.

게미미
X axis display -15 ,
Y axis display 0 .
7) Process Hole B
8) Move the machine tool to Point C.

X axis display 0 ,
Y axis display 20.

9) Process Hole C
10) Enter the display mode of the third
 UCS.

- 1 IITIUT

Key (园
11) Move the machine tool to point 3.

X axis display 0 ,
Y axis display 0 .

## $\square \rightarrow$ IID <br> $\square$


12) Enter PCD function, process the six small holes distribute uniformly on the circle center at Point 3 . Key
13) The processing of the six small holes has been finished, return to Point D, the display should be:

For PCD function, please refer to the related sections.

## V. The Clearing of Subsidiary Zero Positions and Other Related Problems.

## 1. The Clearing of Subsidiary zero positions

In absolute state (ALE state), key 10 times continuously, the memory about all the subsidiary zero positions will be cleared, the 200 subsidiary zero positions will become the same point of the zero position in the absolute state.

## 2. Reset during a subsidiary zero position is being used

A subsidiary zero position is being used of course under the display mode of the corresponding UCS, resetting in this state is actually to reset a new subsidiary zero position. The point at which the resetting operation act become the new subsidiary zero position, and the new subsidiary zero position replacing the
original subsidiary zero position.

## 3. Turn to one half during a subsidiary zero position is being used

" $1 / 2$ " function may be used under UCS display mode. Turning to one half under the UCS display mode using a subsidiary zero position is actually also resetting a new subsidiary zero position. After the operation of turning to one half act, the original subsidiary zero position will be replaced by the new subsidiary zero position is center between the original subsidiary zero position and the point at which the operation act.

# F. PCD Circle Equally Dividing Holes 

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## Circular arc equally Dividing Function(PCD Function)

This function may be used to divide a circular arc equally, for example in the processing of drilling holes distributed uniformly on a flange. After selecting this function, the message window will prompt for various parameters to be defined for the operator.

The following are parameter to be defined.


## 1. The position of the circle center.

The position of the circle center (CT POS) means the position of the circle center with respect to the center of the tool just after tool setting and clearing, such as the position of Point O with respect to
 Point A in Fig. (A).

## 2. Diameter(DIA): The Diameter of the circle to be divided equally.

## 3. The number of holes(NUMBER):

The number of holes equally dividing the circle. For the example shown in Fig. (B), 5 points from
 point 1 to Point 5 must used to divide the arc from $0^{\circ}$ to $180^{\circ}$ into 4 equal sections. So, 9 points must be used to divide the whole circle into 8 equal sections, and Point 9 will coincide with Point 1. As shown in the Fig., in order to drill 8 hole on the circle into 8 sections, the number of point to be entered should be 9 .
4. The start angle (ST ANG): The angle of the start point of the circular arc to be divide equally.
5. The end angle (ED ANG): The angle of the end point of the circular to be divided equally.

Note: For the definition of the start angle (ST ANG) and end angle (ED ANG), refer to the section "To recognize the start and end angle of a circular arc".

Tale the processing of the circular working-piece in Fig. (c) as example:

1) At first, find out the center position of the working piece and finish tool setting reset.

Key to enter PCD function．

2）Enter the center position of the circular $\square$ ［ITT TPIT］ $\mathrm{Key} \underset{(\mathrm{X})}{\mathrm{X}} \rightarrow \mathrm{O} \rightarrow$（ENT）


Key（J），next step．

3）Enter the diameter of the circular arc．
Key（1）$\rightarrow 0 \rightarrow 0 \rightarrow 0$
Key（r），next step．


$\square$

4）Enter the number of points equally dividing the arc．
Fig．（c），we can consider it as 6 points is used to divide the arc from 0 to $300^{\circ}$ into $\square N \mid[M \mid B E E R \square$
$5^{\circ}$ equal section．
Key （6）$\rightarrow$（ax）


INUMBEIRD

Key（3），next step．
It is also possible to consider as 7

points in points in used to divide the whole $\square$ circle into 6 equal sections．

Key（7）$\rightarrow$
Key（3），next step．
5）Enter the start angle．
Key（O）$\rightarrow$（air）
Key（J），next step．

पडTT \ANT］

$\square$
$\square$

$\square$（10）

6）Enter the end angle．
If the arc is dividing by 6 points．
$\mathrm{Key}(3) \rightarrow 0 \rightarrow 0$
Key（B），next step．
If the whole circle is divided by 7 point． $\square$
$\mathrm{Key} \rightarrow(3) \rightarrow 0 \rightarrow$（ir
Key（B），next step． 136IDOU
$\square$
7) Enter processing

The display result for dividing the arc into5 equal sections.
$\square$
510 [10 区
$\square$
The display result for dividing the arc Into 6 equal sections.

$\square$ 게밍
9) Key (D) and the position of next processing point will be displayed, just move the machine tool to bring the displayed values on both axes into zero to reach the corresponding processing position.
10) You may quit PCD function at will, just key

# G. Angular Surface Processing 

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## Angular Surface Processing

When the processing of a rather large angular surface is one part of job, the angular processing function can make the job much easier.

## I . Aligning for the bank angle:

When the processing surface is Plane XY as in the case of the fitting shown in Fig. (a), it is necessary to align the working piece for

(a) the bank angle before processing the angular surface. In this case, the angular surface processing function plays its role in aligning the reference plane for the bank angle.

The procedure of aligning for the bank angle:
At first, set the working piece on the machine table with an oblique angle equal roughly the desired bank angle.

1. Key 漛 to enter the angular surface processing function.
2. Select the processing plane-Plane XY.

3. Enter the angle of the angular surface (ANGLE).
4. Move the machine table to let the metering tool(for example, dial indicator) preset on the milling machine come just in contact with the reference plane being aligned, adjust the scale reading into zero, and move the machine table an arbitrary distance along X axis.
5. Key $Y$, refer to the display and move along $Y$ axis until the displayed value become zero.
6. Adjust the angle of the working piece and bring the scale reading into zero.

For example: Align the bank angle of the working piece to $45^{\circ}$ as shown in Fig. (b).

1) Set the working piece on the machine table with a bank angle equal roughly $45^{\circ}$

LINE-MY Key 膡
2) Select Plane XY.

Key ENT
LINE-- $K Y$
3) Enter the angle of the angle surface


Key (D)

4) Move the machine table along $X$ axis.


Let the metering tool come just in contact with the working piece, and adjust the
 scale reading into zero, then move the machine table an arbitrary distance along X axis.

5) The moving distance on $Y$ axis is displayed. $\qquad$ | $M\left\|V^{\prime}\right\| E \mid$ | $\prime$ |
| :--- | :--- | :--- | Key $Y$

\section*{|  |  | $\square$ | $\square$ |
| :--- | :--- | :--- | :--- | :--- |}

6) Move the machine tool along $Y$ axis.

Adjust the bank angle of the working piece, let the reference plane being aligned come just in contact with the metering tool and the scale reading be zero.
7) Move the machine table to bring the displayed value on Y axis into zero.

You may quit the angular surface processing function at will, just key

## II . Processing the angular surface

When the processing plane is Plane XZ or YZ, the angular processing function may prompt in processing the angular surface step by step.

## Processing on using the angular processing function:



When the processing plane is Plane XZ or YZ . At first align the spindle of the machine tool for the bank angle, finish tool setting, and key 漛) to enter the angular processing function.


1．Select Plane XZ or YZ．
2．Enter the diameter of the tool（DIA）．
3．Enter the start point（ST POS）．
4．Enter the end point（ED POS）．
5．You may quit the angular surface processing function at will，just key（圈）

## Refer to the example：

1）Align for the bank angle，finish tool setting，and key 漛．

## LIINET－$x^{\prime}$ Y

2）Select the processing plane
Key［a］
Select Plane XZ
LINE－ K Z
Key（3in）
3）Enter the diameter of the tool

$\square$


Key（3）


4）Enter the start point
Key

 －I Plllll

Key（J）
5）Enter the coordinates of the end point．
Key


Key（B）
6）Enter processing state
$\square$
－IT18000

－－I 旧，吅（

Key (1) or (B) and respectively the position of last/next processing point will be displayed.

You may quit the angular processing function at will, just key

# H. The Progressive Progressing of rectangular Inner chamber 

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## The progressive progressing of rectangular inner chamber

When the job is to process the inner chamber of the fitting shown by the working drawing of Fig. (1), the progressive inner chamber processing function may be used; and referring to the prompts the operator can operate easily. As shown in Fig. (3), the processing starts from the center of the inner chamber and goes on along the arrow direction.

## Operation procedure:

1. Key 漛to enter the progressive inner chamber processing function.
2. Enter the diameter of the tool (DIA).
3. Enter the position of the inner chamber (CT POS) (the position with respect to center of the tool).
4. Enter the size of the inner chamber.

(1)

5. Enter processing state.

The operation procedure in an example:
The processing of the inner chamber of the fitting shown in Fig. (1).

(3)

1) Finish tool setting as shown in Fig. (2), reset, and key to enter the function. $\square$
2) Enter the diameter of the tool
 Key (6) $\longrightarrow$ (aix) Key (B)
$\square$
(2)
$\square$
3) Enter the position of the center of the inner chamber.


 Key (B)
4) Enter the size of the inner chamber Key
 Key (B)


5) Enter processing state.


6) Move the machine table to bring the displayed values on both X - and Y-axes

|  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |


| $\square$ | $\left.Y_{0}\right)$ |
| :--- | :--- | :--- | :--- | into zero.

7) Key (v) to display the processing position of next step, refer to the prompts and move the machine to bring the displayed values on both X - and Y - axes into zero.

You may quit the progressive inner chamber processing function at will, just key

## I. The Function Calculator Function

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## The Calculation function

Some time it is necessary to calculate out some values during the processing, SDS2MS Series digital display boxes are provided with simple Calculation function.

## The details are as following:

All the resulted value is displayed on X axis.
CoiR Is the Calculation function key, key it to enter the Calculation function, during using the Calculation function you may quit the function at will, just key the same key.

Q, the key for Calculating the square root.
[ac), the key for "inverting" trigonometric functions, key it and then key a trigonometric function key for Calculating the inverse trigonometric function.

[©A), key for canceling last input and the result of last calculation.
( $\Delta \rightarrow X$, data axis transferring, key them in succession to transfer the resulted value on.
$\rightarrow$ 园, quit data axis transferring.
Example: Key (cire to enter calculation function.
Perform the following calculation: $10+10 \div 2 \times 5=35$


Calculate: $\sin 45^{\circ}=0.707$
(4) $\rightarrow$ (5) $\rightarrow 0.707$

Calculate: $\operatorname{arc} \sin 0.707=44.991$


Make the following calculation:
The distance AB in the figure $=\sqrt{ } \frac{0^{2}+30^{2}}{}=31.623$
$(1) \rightarrow(0) \rightarrow(0) \rightarrow(0) \rightarrow(0)$

$$
\rightarrow \square \rightarrow(3 \rightarrow \square \rightarrow \square 1.623
$$



Display for the result:


Transfer the value 31.623 to Y axis.
Key 园 $\square$
$\square$
Key Y


As shown in the figure, the distance $\mathrm{AB}=31.623$, the tool is at Point A , move the machine table to bring the displayed value into zero, the position of Point $B$ is reached, the processing of Hole B may start.

Quit the resulted value axis transferring function, enter the calculation function again.

Key $(\mathbb{C A} \rightarrow \Delta$



Key (ciR) to quit the calculation function.

Notes: When the value of input or calculation runs over, the information window display "CTR E", means the result of calculation is wrong, press ©A key can resume.

# J. N3 Function 

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the function is suit for Z axis vertical slope machining.
There are four machining mode, as following example:



(1) $\Delta Z=0.1$
$A=60^{\circ}$
(2) $\Delta Z=0.1$
$A=120^{\circ}$
(3) $\Delta Z=-0.1$
$A=-120^{\circ}$
(4) $\Delta Z=-0.1$
$A=-60^{\circ}$

Operation steps was show as fallow: (Take the processing plane XZ as an example)

1) Move the tool to the start point,

Key (X0) (plane YZ).
2) Key (
3) Key , select the processing plane.

| - $x_{2}$ |
| :---: |

(B)
$\square$
네N000

$\square$
4) Select plane XZ, Key ENT to ensure $\square$
5) Enter the angle.

Key (6) $\rightarrow$ (0) $\rightarrow$ (ENT)
Key (B), next setp

6) Enter the feeding of $Z($ delta $Z$ )

Key $0 \rightarrow \rightarrow(1) \rightarrow$ ENT
Key (D), start processing.

$\square$
(Note: When processing, delta $\mathbf{Z}$ of each step is equal.)
7) Point 1 , move axis $X$ to 0 , move axis Z 0.1 mm forward.
$\square \triangle$ 吅

| \|N| |
| :--- | :--- | :--- | :--- |

데 1000 (

Key (J), next point.
8) Point 2, move axis $X$ to 0 , move axis Z 0.1 mm forward.
$\square$

 Key (3), next point.
9) Point 3, move axis $X$ to 0 , move axis Z 0.1 mm forward. Key [8], next point.

The last point
10) The last point, move axis $X$ to 0 , move axis Z 0.1 mm forward.
11) Key 圆, quit N3 function, digital readout show the current


멤ㅁ뭉
$\square$
메11900 XY value.
12) Validate the value using the equation bellow:

$$
X_{(I)}=\frac{\Delta Z}{\operatorname{tg} A} \times I \quad \Delta X=\frac{\Delta Z}{\operatorname{tg} A}
$$

$Z_{(I)}=\Delta Z \times I$
I Step number.
Delta X : feed of axis X between each step.
Delta Z: feed of axis $Z$ between each step.
XI: displacement of axis X in the Ith point.
ZI : displacement of axis Z in the Ith point.
(Note: the processing on plane $Y Z$ is the same with plane $X Z$.)

## Additional sheet:

## I . What the user must know:

1. The digital display box must be handle carefully.
2. The box must be grounded properly.
3. Power voltage selection: AC $80 \mathrm{~V} \sim 260 \mathrm{~V}$

$$
50 \mathrm{~Hz} \sim 60 \mathrm{~Hz}
$$

4. Power consumption: 25VA
5. Working temperature: $0^{\circ} \mathrm{C} \sim 45^{\circ} \mathrm{C}$
6. Storage temperature: $-30^{\circ} \mathrm{C} \sim 70^{\circ} \mathrm{C}$
7. Relative humidity: $<90 \%\left(20 \pm 5^{\circ} \mathrm{C}\right)$
8. Weight: $\approx 830 \mathrm{~g}$
9. There must not obviously be corrosive gases around the box.
10. Number of coordinates: 2 coordinates, 3 coordinates.
11. Display: 7 digit with plus and minus symbol display (2 axes or 3 axes), the message window displays by means of 8 star character display device.
12. Frequency multiplication: 4 X
13. Allowable input signal: TTL square wave.
14. Allowable input signal frequency: $\leqslant 5 \mathrm{M} \mathrm{Hz}$
15. Length resolution: $5 \mu \mathrm{~m}, 1 \mu \mathrm{~m}$.
16. Operation keyboard: Sealed diaphragm touch keys.
17. The input interface definition of Length Measuring Linear Raster Ruler:( 9_pin socket)

| Pin | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Signal | Null | 0 V | Null | Null | Null | A | +5 V | B | Z |



## II. Trouble shooting and handling:

Troubleshooting of Grating Ruler and Digital display Meter
The following troubleshooting is primary only. If there are still problems, do not dismantle them by yourself, seek help from our company or corresponding agents.

| Symptom of failure | Source of failure | Troubleshooting |
| :---: | :---: | :---: |
| Digital display meter does not display | 1. Is it connected to power supply? <br> 2. Is power switch closed? <br> 3. Is appropriate mains voltage used? <br> 4. Shorting of power supply inside grating ruler. | 1. Check power wire, then switch on power supply. <br> 2. Close the power switch. <br> 3. Mains voltage should be within 60~260V. <br> 4. Disconnect plug of grating ruler. |
| Enclosure of digital display meter is charged. | 1. Is enclosure of machine tool and digital display meter well grounded? <br> 2. Is there electric leakage from 220 V power supply to the ground? | 1. Well ground enclosure of machine tool and digital display meter <br> 2. Check 220V power supply. |
| One axis of digital display meter does not count. | 1. Exchange with the grating ruler on the other axis, and then operate to see if it no longer counts. <br> 2. Is digital display meter in some special function? | 1. If counting is normal failure of grating ruler. <br> If counting is abnormal failure of digital display meter. <br> 2. Exit special function. |


| Symptom of failure | Source of failure | Troubleshooting |
| :---: | :---: | :---: |
| Grating ruler does not count | 1. Grating ruler falls outside the usable range of length, reading head cracked up. <br> 2. Reading head of grating ruler rubs ruler enclosure, and aluminum chips piled up. <br> 3. Too much gap between reading head of grating ruler and ruler body. <br> 4. Metal hose parts of grating ruler (plugs, hoses, connectors) burnt, squeezed, broken to cause shorting or breaking of inner circuits. <br> 5. Time of service of grating ruler too long, some inner parts or components go wrong. | 1. Repair the grating ruler. <br> 2. Repair the grating ruler. <br> 3. Repair the grating ruler. <br> 4. Repair the grating ruler. <br> 5. Repair the grating ruler. |
| Grating ruler does not count sometimes. | 1. Carriage body of grating ruler apart from friction ball. <br> 2. Some part of small grating piece inside reading head of grating ruler wears out. <br> 3. There is dirt on some part of grating inside enclosure of grating ruler. <br> 4. Insufficient elasticity of carriage steel wire inside reading head of grating ruler. | 1. Repair the grating ruler. <br> 2. Repair the grating ruler. <br> 3. Repair the grating ruler. <br> 4. Repair the grating ruler. |

## III. Structural principle

Our linear encoder and digital readout are high technologic production that is combined with photo electronic technology, precision mechanical technology, microelectronic technology and computer technology, and so on. The customer without being trained may not repair this system. The structural principle is as follows.


## IV. Install figure


notice: 1, cliping the power and signal wire to avoid stumbling.
2, install height is 1350 mm from the operator standing floor.
V. product packaging bill

1, a piece of SDS2MS series digital readout
2. a piece of power wire

3, a copy of operating instruction
4, A copy of verified certificate
5. A piece of dustproof cover

6, a piece of wire clip
7, a piece of bracket

Dear users:
Thank the purchase and use of Guangzhou Lokshun CNC Equipment Ltd' product! In order to make our services make you more satisfied after the purchase, please read the following instructions:

Products shall be delivered with "Three Guarantees" and 15-day limited replacement and free repair within the period of one warranty year (from date of sale). Accessories must be complete in replacement:

The following few services are not free:
1, over one year warranty;
2, abnormal damage due to failure of comply with requirements of using, maintain and storage;

3, damage caused by the unauthorized mender;
4, without a valid invoice (except the products can be proved in warranty (1) year);

5, damage caused by irresistible force.

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